

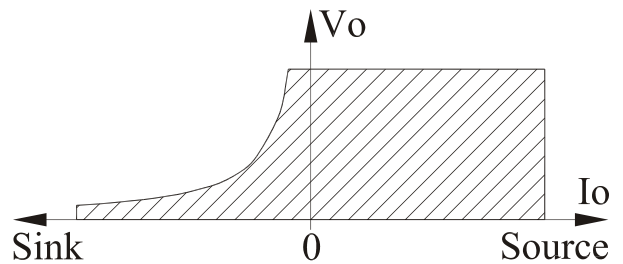


POWER SINK FOR 2 QUADRANT OPERATION options for SM800, SM1500, SM3000 and SM6000

The Power Sink Option permits the power supply to absorb bursts of power fed back to the unit. An internal module senses the status of power supply and sinks current across the output terminals, thus maintaining a constant output voltage.

The Power Sink Option allows a faster response when the power supply is step programmed to a lower voltage at small load conditions.

- Can absorb 10-20% of the unit power. For example, the SM6000 can absorb 700 W.
- Maintains output voltage setting regardless output power is positive or negative (source and sink)
- Ideal solution for supplying electric motors with PWM-speed control. These systems often return power to the power supply during a braking action
- Ideal solution for ATE systems requiring fast down programming at no load conditions
- Generation Automotive waveforms (fast)



Delta Elektronika Power Sinks

See table below for available Delta Elektronika Power Supplies with Power Sink option. All Power Sinks have electronically limited peak power and maximum current. The module shuts down in case of thermal overload (the unit itself continues operation). The overload condition is indicated with a LED on the front panel and with a status output.

SM800 - series Power Sink Peak Power / Maximum current	SM7.5-80 option P245 140 W / 36 A	SM18-50 option P246 140 W / 36 A	SM70-AR-24 option P247 140 W / 25 A	SM400-AR-4 option P248 140 W / 5 A	-
SM1500 - series Power Sink Peak Power / Maximum current	SM15-100 option P202 200 W / 40 A	SM35-45 option P203 200 W / 40 A	SM52-30 option P204 200 W / 30 A	SM52-AR-60 option P205 200 W / 40 A	SM70-22 option P206 200 W / 30 A
SM3000 - series Power Sink Peak Power / Maximum current	SM15-200D option P127 300 W / 70 A	SM30-100D option P128 300 W / 70 A	SM45-70D option P129 300 W / 70 A	SM70-45D option P130 300 W / 45 A	-
SM6000 - series Power Sink Peak Power / Maximum current	SM15-400 option P230 700 W / 140 A	SM30-200 option P231 700 W / 140 A	SM45-140 option P232 700 W / 140 A	SM60-100 option P233 700 W / 100 A	SM70-90 option P234 700 W / 100 A

Why does a DC Power Supply need a Power Sink

Modern Loads and Test-Systems become more demanding

In the past a DC power supply only needed to *deliver* power, now loads can *return* power. The only way to cope with this new challenge is integrating an electronic load in the power supply, called a Power Sink. Without the sink-capability the output voltage will start rising and get out of control.

Reverse Current

DC Motors are more and more controlled by a PWM (Pulse Width Modulation) circuit; the advantage is a flexible loss-less speed control. Car makers make use of this technique to make new solutions possible for pumps, electric steering, brakes, windscreen wipers, hybrid cars and more. Also energy is conserved, this means less heat dissipation. The special behavior of a PWM controlled motor is the return of power during a braking action. In fig. 1 you can see the typical load current, in phase I the motor accelerates; in phase II it has constant speed with a certain load and in phase III the motor brakes and the current becomes negative.

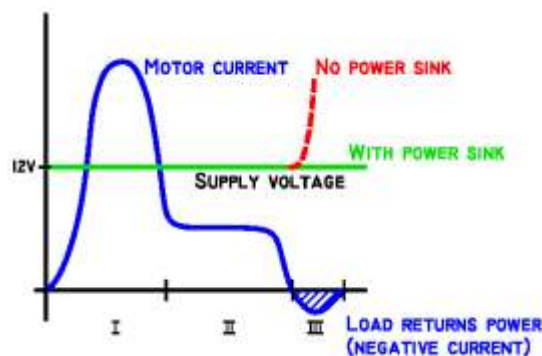


Fig. 1
Typical load current
PWM - controlled DC motor

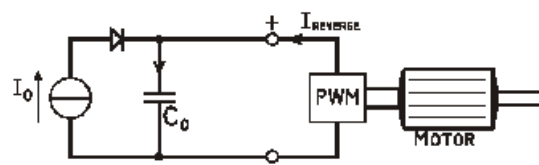


Fig. 2
Simplified output circuit normal power supply.
Braking power of motor charges
output-capacitor

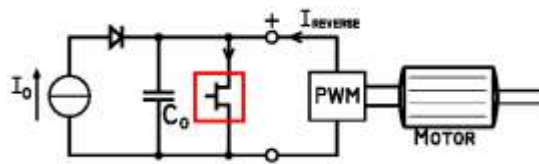


Fig. 3
Braking power of motor absorbed by Power Sink
equipped power supply.
No voltage rise

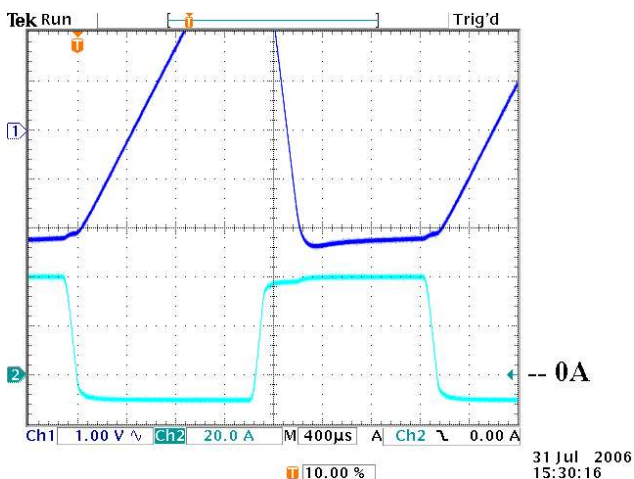


Fig. 4

Without Power Sink
Uncontrolled voltage rise when the load current
goes negative

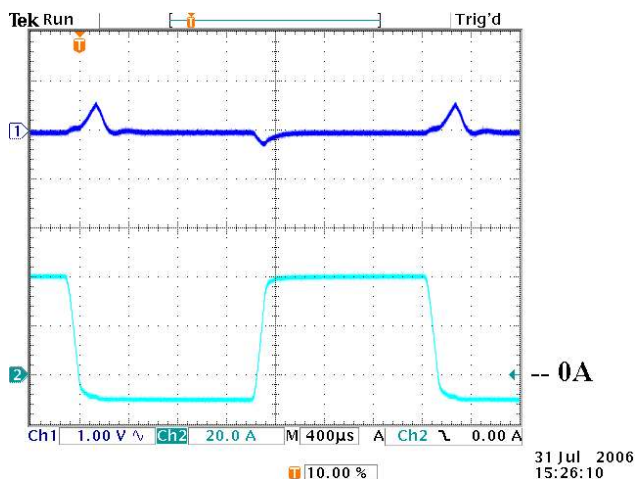


Fig. 5

Dynamics reaction of Power Sink
Load current switches between positive
and negative

Fast Down Programming & Automotive

Test Systems require a test-time as short as possible. For each new item to be tested the voltage often has to be programmed down to zero. A normal power supply has a problem because it cannot quickly discharge the output capacitor C_o . The circuit in fig. 6 shows that only the load can discharge C_o .

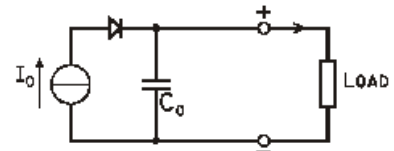


Fig. 6
Simplified output circuit
Normal power supply

A Power Sink as in fig. 7 will make it possible to do fast down-programming at light or no-load conditions. See fig. 8 and fig. 9 to compare the results. Also for generating fast simulation voltages, like the battery voltage of a starting car (ISO7637), a Power Sink is indispensable.

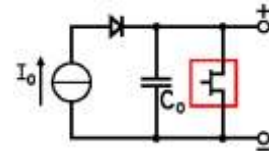


Fig. 7
Simplified output circuit
Power Sink equipped power supply

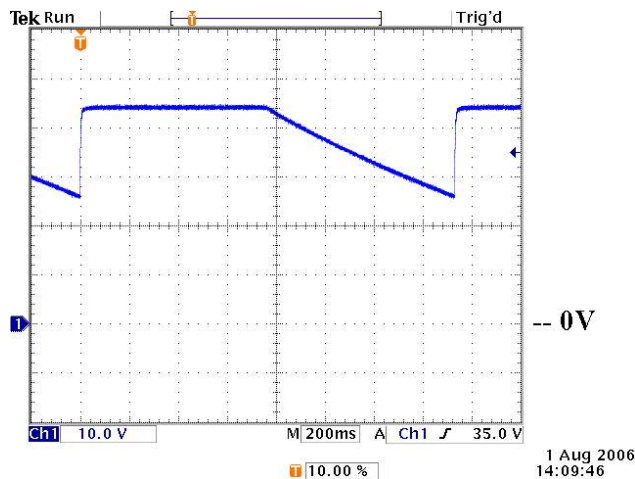


Fig. 8
Down programming at no load
Normal power supply
Voltage falls very slowly

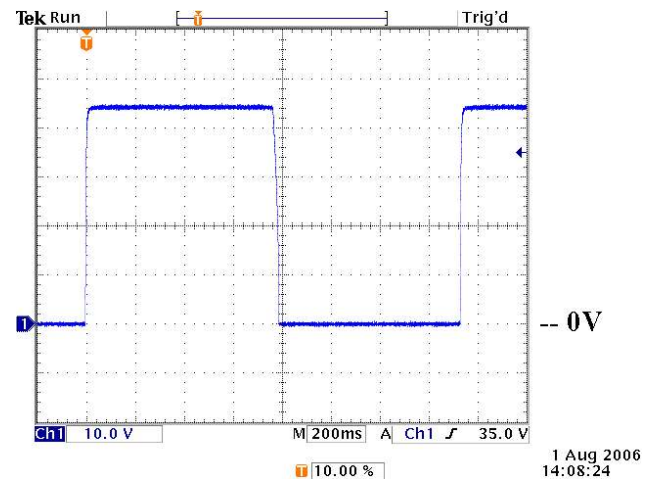


Fig. 9
Down programming at no load
Power Sink equipped power supply
Short fall-time



SM52-AR-60

SM800 - Series

Order code: SM7.5-80 - P245
 SM18-50 - P246
 SM70-AR-24 - P247
 SM400-R-4 - P248



SM70-AR-24

POWER SINK SPECIFICATIONS	SM7.5-80 option P245	SM18-50 option P246	SM70-AR-24 option P247	SM400-AR-4 option P248
Sink Power Rating <i>max. peak power (electronically limited)</i> <i>max. continuous power ($T_{amb.} = 25^{\circ}\text{C}$)</i> <i>max. continuous power ($T_{amb.} = 50^{\circ}\text{C}$)</i>	140 W 140 W 110 W			
Max. duration Sink Peak Power $P_{sink} = 140\text{ W}$, $T_{amb.} = 25^{\circ}\text{C}$ Duty Cycle for use at Peak Power $P_{sink} = 140\text{ W}$, $T_{amb.} = 25^{\circ}\text{C}$	continuous 100%			
Max. Sink Current $(V_o \geq 2\text{ V and } P \leq 140\text{ W})$	Limited at 36 A	Limited at 36 A	Limited at 25 A	Limited at 5 A
Protection	Electronic Power Limit (140 W) limits the current. The temperature of the Power Sink is fan controlled and the circuit shuts down in case of thermal overload.			
Recovery time / Deviation $V_o = 6\text{ V}$, $I_o: +30\text{ A} \rightarrow -10\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 15\text{ V}$, $I_o: +20\text{ A} \rightarrow -4\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 24\text{ V}$, $I_o: +15\text{ A} \rightarrow -2\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 60\text{ V}$, $I_o: +9\text{ A} \rightarrow -1\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 150\text{ V}$, $I_o: +3\text{ A} \rightarrow -0.5\text{ A}$ <i>recovery within 1.0 V / deviation:</i> $V_o = 350\text{ V}$, $I_o: +1\text{ A} \rightarrow -0.1\text{ A}$ <i>recovery within 1.0 V / deviation:</i> <i>(load current switches from positive to negative)</i>	$di/dt = -0.7\text{ A}/\mu\text{s}$ 200 μs / 0.15 V - - - - - <i>note: values are typical</i>	$di/dt = -0.7\text{ A}/\mu\text{s}$ 400 μs / 0.25 V $di/dt = -0.5\text{ A}/\mu\text{s}$ 700 μs / 0.20 V - - - - <i>note: values are typical</i>	- $di/dt = -0.5\text{ A}/\mu\text{s}$ 700 μs / 0.85 V $di/dt = -0.4\text{ A}/\mu\text{s}$ 800 μs / 0.75 V $di/dt = -0.3\text{ A}/\mu\text{s}$ 4.0 ms / 0.65 V - - <i>note: values are typical</i>	- - - - $di/dt = -0.1\text{ A}/\mu\text{s}$ 800 μs / 4.0 V $di/dt = -0.05\text{ A}/\mu\text{s}$ 2.0 ms / 2.7 V <i>note: values are typical</i>
Programming Down Speed <i>Fall time at no load (90 - 10%)</i> <i>Fall time at no load without Power Sink</i> Unit with Fast Programming Option <i>Fall time at no load (90 - 10%)</i> <i>Fall time at no load without Power Sink</i>	(7.5 \rightarrow 0 V) 6.5 ms 5 s P245+P250 <i>specifications not yet available</i>	(18 \rightarrow 0 V) 17 ms 6 s P246+P251 <i>specifications not yet available</i>	(70 \rightarrow 0 V) 25 ms 4 s P247+P252 1 ms 760 ms	(400 \rightarrow 0 V) 19 ms 4.5 s P248+P253 <i>specifications not yet available</i>

Notes:

- The maximum sink current at higher voltages will not be the maximum specified current due to the power limit. For example at 30 V the maximum sink current will only be 4.7 A ($30\text{ V} \times 4.7\text{ A} = 140\text{ W} = \text{maximum power}$).
- A higher sink current than the maximum current will cause the output voltage to rise.

SM1500 - Series

Order code: SM15-100 - P202
 SM35-45 - P203
 SM52-30 - P204
 SM52-AR-60 - P205
 SM70-22 - P206



SM52-AR-60

POWER SINK SPECIFICATIONS	SM15-100 option P202	SM35-45 option P203	SM52-30 option P204	SM52-AR-60 option P205	SM70-22 option P206
Sink Power Rating <i>max. peak power (electronically limited)</i> <i>max. continuous power ($T_{amb.} = 25^{\circ}\text{C}$)</i> <i>max. continuous power ($T_{amb.} = 50^{\circ}\text{C}$)</i>	200 W 125 W 80 W				
Max. duration Sink Peak Power $P_{sink} = 200\text{ W}$, $T_{amb.} = 25^{\circ}\text{C}$ Duty Cycle for use at Peak Power $P_{sink} = 200\text{ W}$, $T_{amb.} = 25^{\circ}\text{C}$ $P_{sink} \leq 200\text{ W}$, $T_{on} \leq 20\text{ s}$ t_{on} = time, power dissipation is $> 0\text{ W}$ t_{off} = time, power dissipation is 0 W $P_{av} = P_{peak} \cdot t_{on} / (t_{off} + t_{on})$	max. $t_{on} = 60\text{ s}$, following $t_{off} = 500\text{ s}$ (for cooling down) $t_{on} \leq 20\text{ s}$ / $t_{off} \geq 14\text{ s}$ average power $\leq 130\text{ W}$				
Max. Sink Current $(V_o \geq 2\text{ V and } P \leq 200\text{ W})$	Limited at 40 A	Limited at 40 A	Limited at 30 A	Limited at 40 A	Limited at 30 A
Protection	Electronic Power Limit (200 W) limits the current. The temperature of the Power Sink is fan controlled and the circuit shuts down in case of thermal overload.				
Recovery time / Deviation $V_o = 6\text{ V}$, $I_o: +40\text{ A} \rightarrow -15\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 15\text{ V}$, $I_o: +25\text{ A} \rightarrow -8\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 35\text{ V}$, $I_o: +20\text{ A} \rightarrow -3\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 52\text{ V}$, $I_o: +10\text{ A} \rightarrow -2\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 70\text{ V}$, $I_o: +10\text{ A} \rightarrow -1\text{ A}$ <i>recovery within 100 mV / deviation:</i> <i>(load current switches from positive to negative)</i>	$di/dt = -1.7\text{ A}/\mu\text{s}$ 300 μs / 0.20V $di/dt = -1.6\text{ A}/\mu\text{s}$ 500 μs / 0.15V - - - <i>note: values are typical</i>	$di/dt = -1.7\text{ A}/\mu\text{s}$ 500 μs / 0.45V $di/dt = -1.6\text{ A}/\mu\text{s}$ 600 μs / 0.40V $di/dt = -1.3\text{ A}/\mu\text{s}$ 1.10ms / 0.35V - - <i>note: values are typical</i>	- $di/dt = -1.6\text{ A}/\mu\text{s}$ 640 μs / 0.70V $di/dt = -1.3\text{ A}/\mu\text{s}$ 800 μs / 0.60V $di/dt = -0.7\text{ A}/\mu\text{s}$ 800 μs / 0.60V - <i>note: values are typical</i>	$di/dt = -1.7\text{ A}/\mu\text{s}$ 700 μs / 0.50V $di/dt = -1.3\text{ A}/\mu\text{s}$ 900 μs / 0.45V $di/dt = -0.83\text{ A}/\mu\text{s}$ 1.30ms / 0.35V $di/dt = -0.6\text{ A}/\mu\text{s}$ 1.90ms / 0.35V - <i>note: values are typical</i>	- - $di/dt = -1.3\text{ A}/\mu\text{s}$ 800 μs / 0.70V $di/dt = -0.6\text{ A}/\mu\text{s}$ 1.00ms / 0.70V $di/dt = -0.6\text{ A}/\mu\text{s}$ 1.20ms / 0.50V <i>note: values are typical</i>
Programming Down Speed <i>Fall time at no load (90 - 10%)</i> <i>Fall time at no load without Power Sink</i>	(15 \rightarrow 0 V) 8 ms 2 s	(35 \rightarrow 0 V) 18 ms 5.5 s	(52 \rightarrow 0 V) 10 ms 4 s	(52 \rightarrow 0 V) 45 ms 7.5 s	(70 \rightarrow 0 V) 18 ms 5.5 s
Parallel and Series operation Refer to Power Sink manual for details and restrictions	Using multiple units in parallel operation, only one unit can have a Power Sink. Using multiple units in series operation, all units must have a Power Sink.				

Notes:

- The maximum sink current at higher voltages will not be the maximum specified current due to the power limit. For example at 30 V the maximum sink current will only be 6.7 A ($30\text{ V} \times 6.7\text{ A} = 200\text{ W} = \text{maximum power}$).
- A higher sink current than the maximum current will cause the output voltage to rise.

SM3000 - Series

Order code: SM15-200D - P127
 SM30-100D - P128
 SM45-70D - P129
 SM70-45D - P130



POWER SINK SPECIFICATIONS	SM15-200D option P127	SM30-100D option P128	SM45-70D option P129	SM70-45D option P130
Sink Power Rating <i>max. peak power (electronically limited)</i> <i>max. continuous power ($T_{amb.} = 25^{\circ}\text{C}$)</i> <i>max. continuous power ($T_{amb.} = 50^{\circ}\text{C}$)</i>	300 W 30 W 15 W			
Max. duration Sink Peak Power $P_{sink} = 300\text{ W}$, $T_{amb.} = 25^{\circ}\text{C}$ Duty Cycle for use at Peak Power $P_{sink} = 300\text{ W}$, $T_{amb.} = 25^{\circ}\text{C}$ $P_{sink} \leq 300\text{ W}$, $T_{on} \leq 15\text{ s}$ t_{on} = time, power dissipation is $> 0\text{ W}$ t_{off} = time, power dissipation is 0 W $P_{av} = P_{peak} * t_{on} / (t_{off} + t_{on})$	$\text{max. } t_{on} = 60\text{ s}$, following $t_{off} = 1200\text{ s}$ (for cooling down) $t_{on} \leq 15\text{ s} / t_{off} \geq 150\text{ s}$ average power $\leq 30\text{ W}$			
Max. Sink Current $(V_o > 2\text{ V and } P \leq 300\text{ W})$	Limited at 70 A			Limited at 45 A
Protection	Electronic Power Limit (300 W) limits the current. Sink circuit shuts down in case of thermal overload.			
Recovery time / Deviation $V_o = 6\text{ V}$, $I_o: +80\text{ A} \rightarrow -20\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 15\text{ V}$, $I_o: +40\text{ A} \rightarrow -10\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 24\text{ V}$, $I_o: +20\text{ A} \rightarrow -6\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 42\text{ V}$, $I_o: +20\text{ A} \rightarrow -3.5\text{ A}$ <i>recovery within 100 mV / deviation:</i> $V_o = 60\text{ V}$, $I_o: +10\text{ A} \rightarrow -2.5\text{ A}$ <i>recovery within 1.0 V / deviation:</i> <i>(load current switches from positive to negative)</i>	$di/dt = -1.5\text{ A}/\mu\text{s}$ 200 μs / 0.30 V $di/dt = -1.0\text{ A}/\mu\text{s}$ 500 μs / 0.15 V - - - <i>note: values are typical</i>	$di/dt = -1.5\text{ A}/\mu\text{s}$ 300 μs / 0.60 V $di/dt = -0.9\text{ A}/\mu\text{s}$ 350 μs / 0.30 V $di/dt = -0.5\text{ A}/\mu\text{s}$ 500 μs / 0.30 V - - <i>note: values are typical</i>	- $di/dt = -0.9\text{ A}/\mu\text{s}$ 200 μs / 0.45 V $di/dt = -0.6\text{ A}/\mu\text{s}$ 200 μs / 0.40 V $di/dt = -0.6\text{ A}/\mu\text{s}$ 500 μs / 0.45 V - <i>note: values are typical</i>	- $di/dt = -0.9\text{ A}/\mu\text{s}$ 200 μs / 0.75 V $di/dt = -0.6\text{ A}/\mu\text{s}$ 200 μs / 0.45 V $di/dt = -0.6\text{ A}/\mu\text{s}$ 480 μs / 0.45 V $di/dt = -0.3\text{ A}/\mu\text{s}$ 1.0 ms / 0.50 V <i>note: values are typical</i>
Programming Down Speed Fall time at no load (90 - 10%) Fall time at no load <i>without Power Sink</i>	(15 \rightarrow 0 V) 6 ms 6 s	(30 \rightarrow 0 V) 10 ms 8 s	(45 \rightarrow 0 V) 6 ms 2 s	(70 \rightarrow 0 V) 10 ms 5 s
Parallel and Series operation Refer to Power Sink manual for details and restrictions.	Using multiple units in parallel operation, only one unit can have a Power Sink. Using multiple units in series operation, all units must have a Power Sink.			

Notes:

- The maximum sink current at higher voltages will not be the maximum specified current due to the power limit. For example at 30 V the maximum sink current will only be 10 A ($30\text{ V} \times 10\text{ A} = 300\text{ W} = \text{maximum power}$).
- A higher sink current than the maximum current will cause the output voltage to rise.

SM6000 - Series

Order code: SM15-400 - P230
 SM30-200 - P231
 SM45-140 - P232
 SM60-100 - P233
 SM70-90 - P234



POWER SINK SPECIFICATIONS	SM15-400 option P230	SM30-200 option P231	SM45-140 option P232	SM60-100 option P233	SM70-90 option P234
Sink Power Rating <i>max. peak power (electronically limited)</i> <i>max. continuous power (T_{amb.} = 25 °C)</i> <i>max. continuous power (T_{amb.} = 50 °C)</i>	700 W 550 W 275 W				
Max. duration Sink Peak Power P _{sink} = 700 W, T _{amb.} = 25 °C Duty Cycle for use at Peak Power P _{sink} = 700 W, T _{amb.} = 25 °C P _{sink} <= 700 W, T _{on} <= 40 s t _{on} = time, power dissipation is > 0 W t _{off} = time, power dissipation is 0 W P _{av} = P _{peak} * t _{on} / (t _{off} + t _{on})	max.t _{on} = 80 s, following t _{off} = 600 s (for cooling down) t _{on} <= 40 s / t _{off} >= 12 s average power <= 550 W				
Max. Sink Current (V _O >= 2 V and P <= 700 W)	Limited at 140 A			Limited at 100 A	
Protection	Electronic Power Limit (700 W) limits the current. The temperature of the Power Sink is fan controlled and the circuit shuts down in case of thermal overload.				
Recovery time / Deviation <i>Vo = 6 V, IO: + 200 A → − 80 A recovery within 100 mV / deviation:</i> <i>Vo = 15 V, IO: + 90 A → − 30 A recovery within 100 mV / deviation:</i> <i>Vo = 24 V, IO: + 50 A → − 12 A recovery within 100 mV / deviation:</i> <i>Vo = 42 V, IO: + 20 A → − 10 A recovery within 100 mV / deviation:</i> <i>Vo = 60 V, IO: + 20 A → − 5 A recovery within 100 mV / deviation:</i> <i>(load current switches from positive to negative)</i>	di/dt= −5A/μs 250 μs / 0.40V di/dt= −3.5A/μs 550 μs / 0.25V - - - <i>note: values are typical</i>	di/dt= −5A/μs 350 μs / 0.75V di/dt= −3.5A/μs 550 μs / 0.45V di/dt= −1.8A/μs 650ms / 0.36V - - <i>note: values are typical</i>	- di/dt= − 3.5A/μs 650 μs / 0.90V di/dt = −1.8A/μs 750 μs / 0.60V di/dt = −1.2A/μs 880 μs / 0.75V - <i>note: values are typical</i>	- di/dt = −3.5A/μs 650 μs / 1.10V di/dt = −1.8A/μs 750 μs / 0.70V di/dt=−1.2A/μs 880 μs / 0.80V di/dt = −0.9A/μs 1.2ms / 0.70V <i>note: values are typical</i>	- di/dt= −3.5A/μs 650 μs / 1.10V di/dt= −1.8A/μs 800 μs/0.75V di/dt=−1.2A/μs 900 μs /0.80V di/dt=−0.9A/μs 1.2ms / 0.70V <i>note: values are typical</i>
Programming Down Speed <i>Fall time at no load (90 - 10%)</i> <i>Fall time at no load without Power Sink</i>	(15 → 0 V) 6 ms 3.5 s	(30 → 0 V) 10 ms 5.5 s	(45 → 0 V) 4.5 ms 3 s	(60 → 0 V) 9.5 ms 5.5 s	(70 → 0 V) 10.5 ms 6 s
Parallel and Series operation Refer to Power Sink manual for details and restrictions	Using multiple units in parallel operation, only one unit can have a Power Sink. Using multiple units in series operation, all units must have a Power Sink.				

Notes:

- The maximum sink current at higher voltages will not be the maximum specified current due to the power limit. For example at 30 V the maximum sink current will only be 24 A ($30\text{ V} \times 24\text{ A} = 700\text{ W} = \text{maximum power}$).
- A higher sink current than the maximum current will cause the output voltage to rise.